ESTIMATION OF THE VARIANCE OF PARTIAL SUMS OF DEPENDENT PROCESSES

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ABSTRACT. We study subsampling estimators for the limit variance

$$\sigma^2 = \operatorname{Var}(X_1) + 2\sum_{k=2}^{\infty} \operatorname{Cov}(X_1, X_k)$$

of partial sums of a stationary stochastic process $(X_k)_{k\geq 1}$. We establish L_2 -consistency of a non-overlapping block resampling method. Our results apply to processes that can be represented as functionals of strongly mixing processes. Motivated by recent applications to rank tests, we also study estimators for the series $\operatorname{Var}(F(X_1))+2\sum_{k=2}^{\infty} \operatorname{Cov}(F(X_1), F(X_k))$, where F is the distribution function of X_1 . Simulations illustrate the usefulness of the proposed estimators and of a mean squared error optimal rule for the choice of the block length.

1. INTRODUCTION AND MAIN RESULTS

Let $(X_i)_{i\geq 1}$ be a stationary ergodic sequence of random variables with mean μ and finite variance, satisfying the central limit theorem, i.e.

$$\frac{1}{\sqrt{n}} \sum_{i=1}^{n} (X_i - \mu) \xrightarrow{\mathcal{D}} N(0, \sigma^2),$$

where the limit variance σ^2 is given by the formula

(1)
$$\sigma^2 = \operatorname{Var}(X_1) + 2\sum_{k=2}^{\infty} \operatorname{Cov}(X_1, X_k).$$

For practical applications of the central limit theorem, e.g., for calculation of confidence intervals or testing hypothesis concerning the mean, we need to estimate the variance σ^2 .

We investigate the properties of a subsampling estimator of σ . Given observations X_1, \ldots, X_n and a block length $l = l_n$, we define the overall mean and the block means as

$$\bar{X}_n = \frac{1}{n} \sum_{j=1}^n X_j$$
, and $\frac{1}{l} S_i(l) = \frac{1}{l} \sum_{j=(i-1)l+1}^{il} X_j$,

respectively. By the central limit theorem, $(S_i(l) - l\mu)/\sqrt{l}$ converges in distribution to $N(0, \sigma^2)$ as l goes to infinity, and thus $E|S_i(l) - l\mu|/\sqrt{l} \to \sigma\sqrt{2/\pi}$. Thus, it is natural to

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estimate σ by the arithmetic mean of $\sqrt{\frac{\pi}{2}} \frac{|S_i(l)-l\mu|}{\sqrt{l}}$, $i = 1, \ldots, [n/l]$. Replacing the unknown mean μ by the sample mean \bar{X}_n , we obtain

(2)
$$\hat{B}_n = \frac{1}{[n/l]} \sqrt{\frac{\pi}{2}} \sum_{i=1}^{[n/l]} \frac{|S_i(l) - l\bar{X}_n|}{\sqrt{l}}$$

as an estimator for σ . In what follows we will always write $k_n = \lfloor n/l_n \rfloor$ for the number of full blocks of length l_n in the set $\{1, \ldots, n\}$.

Subsampling estimators of the limit variance σ^2 of the arithmetic mean of a stationary stochastic process have been studied by various authors under different assumptions concerning the dependence structure. Carlstein (1986) investigated α -mixing processes and the estimator

(3)
$$\hat{B}_n^{(2)} = \frac{1}{[n/l]} \sum_{i=1}^{[n/l]} \left(\frac{|S_i(l) - l\bar{X}_n|}{\sqrt{l}} \right)^2$$

for σ^2 . Peligrad and Shao (1995) studied properly normalized means of *p*-th powers of $|S_i(l) - l\bar{X}_n|/\sqrt{l}$ as an estimator for σ^p in the case of ρ -mixing processes. They consider overlapping blocks, i.e.

$$\tilde{B}_{n}^{(p)} = \frac{c_{p}}{n-l+1} \sum_{i=0}^{n-l} \left(\frac{|\tilde{S}_{i}(l) - l\bar{X}_{n}|}{\sqrt{l}} \right)^{p},$$

where $\tilde{S}_i(l) = \sum_{j=i+1}^{i+l} X_j$. Peligrad and Suresh (1995) studied the same estimator, in the case p = 1, for associated processes. Doukhan et al. (2010) investigated the case of weakly dependent (in the sense of Doukhan and Louhichi, 1999) processes.

In this paper, we extend the above mentioned results to processes that can be represented as functionals of strongly mixing processes. We assume that $(X_i)_{i\geq 1}$ can be written as $X_i = f((Y_{i+k})_{k\in\mathbb{Z}})$ for all $i \geq 1$, where $f : \mathbb{R}^{\mathbb{Z}} \to \mathbb{R}$ is a measurable function and where $(Y_i)_{i\geq 1}$ is an α -mixing process. Recall that a process $(Y_i)_{i\geq 1}$ is called α -mixing (or strongly mixing) if

$$\alpha_k = \sup_{n \ge 1} \sup_{A \in \mathcal{F}^n_{-\infty}, B \in \mathcal{F}^\infty_{n+k}} |P(A \cap B) - P(A) P(B)| \to 0$$

as $n \to \infty$. Here \mathcal{F}_k^m denotes the σ -field generated by the random variables $Y_k, Y_{k+1}, \ldots, Y_m$. The coefficients α_k are called mixing coefficients. In addition, we have to require that the function $f : \mathbb{R}^{\mathbb{Z}} \to \mathbb{R}$ defined above is continuous in a suitable sense. Define

$$\psi_m = E |f((Y_{i+k})_{k \in \mathbb{Z}}) - E(f((Y_{i+k})_{k \in \mathbb{Z}})|Y_{i-m}, \dots, Y_{i+m})|^{\frac{2+\delta}{1+\delta}} \phi_m = E |f((Y_{i+k})_{k \in \mathbb{Z}}) - E(f((Y_{i+k})_{k \in \mathbb{Z}})|Y_{i-m}, \dots, Y_{i+m})|.$$

In what follows, we will have to make assumptions concerning the behavior of the coefficients α_m , ψ_m and ϕ_m as $m \to \infty$.

Functionals of α -mixing processes cover most of the standard examples of weakly dependent processes known in the literature, for example ARMA- and GARCH-processes from time series analysis, many Markov processes and hidden Markov models, the sequence of digits and remainders in continued fraction expansion, and many chaotic dynamical systems, such as expanding, piecewise monotone maps of the unit interval. Details can be found, e.g., in Borovkova et al. (2001) and in Bradley (2007). **Theorem 1.1.** Suppose $(X_k)_{k\geq 1}$ is a stationary process that can be expressed as a functional of an α -mixing process. Suppose that $E|X_1|^{2+\delta} < \infty$ for some $\delta > 0$ and that the approximation coefficients $(\psi_k)_{k\geq 1}$ satisfy

$$\sum_{k=1}^{\infty} (\psi_k)^{\frac{1+\delta}{2+\delta}} < \infty$$

and the mixing coefficients $(\alpha_k)_{k\geq 1}$ satisfy $\alpha_k = O(k^{-\mu})$ for some $\mu > (2+\delta)^2/\delta$. Then, for any sequence $(l_n)_{n\geq 1}$ satisfying $l_n \nearrow \infty$ and $l_n = o(n)$, we have $\hat{B}_n \to \sigma$ in L_2 .

Dehling and Fried (2012) study robust non-parametric tests for structural breaks in time series. They consider the model $X_i = \xi_i + \mu_i$, where (ξ_i) is a stationary stochastic process and $(\mu_i)_{i>1}$ is a sequence of unknown constants. The hypothesis of interest is

$$H_0: \quad \mu_1 = \ldots = \mu_n,$$

to be tested against the alternative $\mu_1 = \ldots = \mu_{n_1} \neq \mu_{n_1+1} = \ldots = \mu_n$. Investigating the asymptotic distribution of the two-sample Hodges-Lehmann test statistic

$$Q_{n_1,n_2}(0.5) = \text{median}\{(X_j - X_i) : 1 \le i \le n_1, n_1 + 1 \le j \le n_1 + n_2\}.$$

Dehling and Fried show that under the above null hypothesis, we have

$$H'(0)\sqrt{\frac{n_1 n_2}{n_1 + n_2}} \frac{Q_{n_1, n_2}(1/2)}{\sqrt{\sigma_F^2}} \xrightarrow{\mathcal{D}} N(0, 1)$$

as $n_1, n_2 \to \infty$. Here $H(x) = P(X_1 - \tilde{X}_1 \leq x)$, where \tilde{X}_1 is an independent copy of X_1 , and

(4)
$$\sigma_F^2 = \operatorname{Var}(F(X_1)) + 2\sum_{k=2}^{\infty} \operatorname{Cov}(F(X_1), F(X_k)),$$

where F is the distribution function of X_1 . For statistical applications, the limit variance σ_F^2 has to be estimated. We can directly apply Theorem 1.1 to the sequence $(F(X_k))_{k\geq 1}$, provided that it satisfies the conditions and that F is known. The latter is generally not the case and thus F has to be replaced by the empirical distribution function \hat{F}_n . In what follows, we will show that this leads to an L_2 -consistent estimator.

Denoting the empirical distribution function by $\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n \mathbb{1}_{\{X_i \leq x\}}$, we define the estimators

(5)
$$D_{n} = \frac{1}{[n/l_{n}]} \sqrt{\frac{\pi}{2}} \sum_{i=1}^{[n/l_{n}]} \frac{|T_{i}(l_{n}) - l_{n} \bar{U}_{n}|}{\sqrt{l_{n}}},$$
$$\hat{D}_{n} = \frac{1}{[n/l_{n}]} \sqrt{\frac{\pi}{2}} \sum_{i=1}^{[n/l_{n}]} \frac{|\hat{T}_{i}(l_{n}) - l_{n} \tilde{U}_{n}|}{\sqrt{l_{n}}},$$

where $\bar{U}_n = \frac{1}{n} \sum_{j=1}^n F(X_j), \ \tilde{U}_n = \frac{1}{n} \sum_{j=1}^n \hat{F}_n(X_j)$, and

$$T_i(l) = \sum_{j=(i-1)l+1}^{il} F(X_j), \qquad \hat{T}_i(l) = \sum_{j=(i-1)l+1}^{il} \hat{F}_n(X_j).$$

Theorem 1.2. Let $(X_k)_{k\geq 1}$ be a stationary process satisfying the assumptions of Theorem 1.1. In addition, assume that $\alpha_n = O(n^{-8})$, $\phi_m = O(m^{-12})$ and that $F(x) = P(X \leq x)$ is Lipschitz-continuous. Then, as $n \to \infty$, $l_n \to \infty$ and $l_n = o(\sqrt{n})$, we have $\hat{D}_n \to \sigma_F$ in L_2 .

2. Simulation study

We investigate the performance of the proposed estimators and compare them to alternatives. The estimators are applied to ARMA(1,1) processes with Gaussian innovations and different parameter settings, which are given in Table 1. For each parameter combination, 1000 samples are drawn, and variance, bias and mean squared error of the estimates are computed. The sample size is n = 500 throughout. Besides comparing several esti-

ĺ	AR	0.5	0.1	-0.1	-0.8	0	0	0	0	0.5	-0.5	0
	MA	0	0	0	0	0.8	0.1	-0.8	-0.1	0.5	-0.5	0

TABLE 1. Types of ARMA(1,1) time series used in the simulation. AR and MA denote the corresponding coefficients of the ARMA(1,1) model in the usual notation.

mators, another question addressed by the simulations is the applicability of Carlstein's rule for choosing the block length. Carlstein (1986) proved it to be optimal in terms of mean squared error for his estimator $\hat{B}_n^{(2)}$, cf. (3), in case of an AR(1) process with known autocorrelation parameter.

The simulation study consists of two stages: the first part is concerned with the estimation of σ^2 , cf. (1), the second part with the estimation of σ_F^2 , cf. (4).

Part 1. We compare \hat{B}_n , cf. (2), the Carlstein estimator $\hat{B}_n^{(2)}$, referred to as CE in the following, and the kernel-based estimator of de Jong and Davidson (2000), abbreviated by JDE in the following. While the former two depend on the block length, the latter is affected by the choice of the kernel and the bandwidth γ_n . We use the Bartlett kernel, which is a common choice due to guaranteed positive semi-definiteness.

To compute mean squared error and bias we compare the estimates to the true value of $\operatorname{Var}(\frac{1}{\sqrt{n}}\sum_{i=1}^{n}X_i) = \operatorname{Var}(X_1) + \frac{2}{n}\sum_{k=2}^{n}\operatorname{Cov}(X_1,X_k)(n+1-k)$, not the infinite series (1). We use the fixed block lengths 1, 2, 5, 10, 30, 50 and 100, and determine the data adaptive block length following Carlstein as follows: An AR(1) process is fit to the sample (regardless of whether it was generated as such) using the R function arima() (R Development Core Team, 2011), and the block length is computed from the estimated autocorrelation parameter. For the JDE, the bandwidths 2.8, 3.5, 4.7, 7.9 and 22.4 are used, corresponding to sixth to second root of n = 500.

Part 2. The second part of the simulation, which deals with the estimation of σ_F^2 , compares \hat{D}_n , cf. (5), to the Peligrad and Shao (1995) estimator, denoted by PSE in the following. Both depend on a block length, but contrary to \hat{D}_n , the PSE is based on overlapping blocks. The data generation is exactly the same as in the first part (sample size, number of repetitions and ARMA parameters), but the data evaluation is different: Each sample is split into halves and the estimate of interest is computed as the mean of the two subsample estimates. This choice is motivated by the intended application to the change-point test by Dehling and Fried (2012). The block lengths considered are 2, 5, 10, 25, 40, 50 for \hat{D}_n and 5, 10, 25, 40, 45 for the PSE. Note that, while a block length 1 is of interest in the first



FIGURE 1. Estimated bias (left) and mean squared error (right) of the estimators \hat{B}_n , CE and JDE as a function of the smoothing parameter; computed from 1000 samples of size 500 generated from an ARMA(0.5, 0.5) model. Gray symbols correspond to the data adaptive block length, plotted at the mean block length of 16.04. The x-axis is on log scale.

simulation, since it yields a variance estimator for independent observation, it leads to data independent estimators in this situation and is hence neglected.

For computing the true value of σ_F^2 we make use of the fact that the population version of Spearman's rho $\rho_s(X,Y) = 12E(F(X)F(Y)) - 3$ equals $\frac{6}{\pi} \arcsin\left(\frac{\rho}{2}\right)$ if X and Y are jointly Gaussian with correlation ρ . This result can be traced back to Pearson (1907); for a newer reference see, e.g., Croux and Dehon (2010). Hence, letting ρ_k denote the correlation of X_1 and X_k , we have

$$\operatorname{Cov}\left(F(X_1), F(X_k)\right) = \frac{1}{12}\varrho_s = \frac{1}{2\pi} \operatorname{arcsin}\left(\frac{\rho_k}{2}\right).$$

Results. As far as the comparison of the estimators is concerned, we get similar results for all ARMA parameter settings, which are exemplified for the σ^2 -estimators at an ARMA(0.5,0.5) process in Figure 1 and for the σ_F^2 -estimators at an MA(0.1) process in Figure 2. The performance of the estimators is generally quite similar. This is also true for \hat{D}_n and the PSE, which may seem surprising, since the PSE, in contrast to \hat{D}_n , uses overlapping blocks. In terms of bias, \hat{B}_n and \hat{D}_n slightly outperform their competitors (see left panels of Figures 1 and 2), but they show slightly bigger variances, leading to a worse mean squared error (see right panels). The choice of the smoothing parameter (block length or bandwidth) has altogether a much larger influence than the choice of the method. We furthermore observe the following: The data adaptive block lengths, which correspond to the gray symbols in the figures, perform quite well in terms of mean squared error (MSE) unless the MA-coefficient is strongly negative. Except for a few cases, σ^2 is always underestimated if all autocorrelations of the underlying process are non-negative and overestimated if all are non-positive. In the white noise case, a block length of 1 is MSE optimal, but other block lengths give very similar results. On the other hand, even for small non-zero AR- or MA-coefficients, not accounting for the dependence substantially impairs the accuracy of the estimation.



FIGURE 2. Estimated bias (left) and mean squared error (right) of the estimators \hat{D}_n and PSE as a function of the block length; computed from 1000 samples of size 500 generated from an ARMA(0.5, 0.5) model. Gray symbols correspond to the data adaptive block length, plotted at the mean block length of 2.7. The x-axis is on log scale.

In summary, all estimators considered show a very similar performance for good choices of the smoothing parameter – despite some considerable differences in their construction. An unfavorable choice of the block length leads to an increase in both, bias and variance, but with varying extents for the different estimators. Based on our results, we suggest to use the estimators \hat{B}_n , \hat{D}_n if one is willing to trade a smaller bias for a bigger variance. The data adaptive block length proposed by Carlstein (1986) seems to yield acceptable results for all block length dependent estimators even if the assumption of an AR(1) process is not met. We also carried out some simulations for other values of n. While the estimators' performance, for fixed block length respectively bandwidth, clearly improves with the sample size, the ranking of the estimators is little affected. Therefore we focus on a fixed sample size here.

3. Proofs

We will first state and prove a special case of Theorem 1.1 where the process $(X_i)_{i\geq 1}$ is α -mixing. We need this result later on in the proof of Theorem 1.1.

Proposition 3.1. Suppose $(X_k)_{k\geq 1}$ is a stationary, α -mixing process with $E(|X_1|^{2+\delta}) < \infty$ for some $\delta > 0$ and mixing coefficients $(\alpha_k)_{k\geq 1}$ satisfying $\alpha_k = O(k^{-\mu})$ for some $\mu > (2+\delta)^2/\delta$. Then, for any sequence $(l_n)_{n\geq 1}$ satisfying $l_n \nearrow \infty$ and $l_n = o(n)$, we have $\hat{B}_n \to \sigma$ in L_2 .

Proof. We will show that $E \left| \hat{B}_n - \sigma \right|^2 \to 0$ as $n \to \infty$. By definition of \hat{B}_n , we get

$$\left|\hat{B}_n - \sigma\right| \le \left|\frac{1}{k}\sqrt{\frac{\pi}{2}}\sum_{i=1}^k \frac{|S_i(l_n) - l_n\,\mu|}{\sqrt{l_n}} - \sigma\right| + \sqrt{\frac{\pi}{2}}\sqrt{l_n}(\bar{X}_n - \mu)$$

As $l_n = o(n)$, we get by the central limit theorem $\sqrt{l_n}(\bar{X}_n - \mu) \to 0$ in L^2 . Thus, it remains to prove that

$$E\left|\frac{1}{k}\sum_{i=1}^{k}\sqrt{\frac{\pi}{2}}\frac{|S_i(l_n)-l_n\,\mu|}{\sqrt{l_n}}-\sigma\right|^2\to 0.$$

By Lemma 4.3 we have

$$E\left(\frac{|S_i(l_n) - l_n \mu|}{\sqrt{l_n}}\right) \to \sqrt{2/\pi} \sigma$$

and thus it suffices to show

$$E\left|\frac{1}{k}\sum_{i=1}^{k}\frac{|S_i(l_n)-l_n\,\mu|}{\sqrt{l_n}}-E\left(\frac{|S_i(l_n)-l_n\,\mu|}{\sqrt{l_n}}\right)\right|^2\to 0.$$

Applying Lemma 4.1 with t = 0 to the stationary α -mixing process $(S_i(l))_{i \ge 1}$, we obtain

$$E \left| \frac{1}{k} \sum_{i=1}^{k} \frac{|S_{i}(l_{n}) - l_{n}\mu| - E|S_{1}(l_{n}) - l_{n}\mu|}{\sqrt{l_{n}}} \right|^{2}$$

$$= \frac{1}{k^{2}l_{n}} E \left| \sum_{i=1}^{k} \left(|S_{i}(l_{n}) - l_{n}\mu| - E|S_{1}(l_{n}) - l_{n}\mu| \right) \right|^{2}$$

$$\leq \frac{C}{k l_{n}} \left(E |\left(|S_{1}(l_{n}) - l_{n}\mu| - E|S_{1}(l_{n}) - l_{n}\mu| \right) |^{2+\frac{\delta}{2}} \right)^{\frac{2}{2+\delta/2}}$$

$$\leq \frac{C}{k l_{n}} \left(E|S_{1}(l_{n}) - l_{n}\mu|^{2+\frac{\delta}{2}} \right)^{\frac{2}{2+\delta/2}} \leq \frac{C}{k} \left(E|X_{1}|^{2+\delta} \right)^{\frac{2}{2+\delta}}$$

where we have used Lemma 4.1 with $t = \delta/2$ in the final step. As $k = k_n \to \infty$, we have thus proved Proposition 3.1.

Proof of Theorem 1.1. Defining

$$\xi_i(s) = E(X_i | \mathcal{F}_{i-s}^{i+s}), \qquad \eta_i(s) = X_i - E(X_i | \mathcal{F}_{i-s}^{i+s}),$$

we decompose $(X_i)_{i\geq 1}$ into a part that is α -mixing and a remaining part, which is small. In addition, we define the corresponding arithmetic means $\overline{\xi}_n = \frac{1}{n} \sum_{i=1}^n \xi_i(s)$ and $\overline{\eta}_n = \frac{1}{n} \sum_{i=1}^n \eta_i(s)$ and the block sums

$$S_i(\xi, l) = \sum_{j=(i-1)l+1}^{il} \xi_j(s), \qquad S_i(\eta, l) = \sum_{j=(i-1)l+1}^{il} \eta_j(s), \qquad i \in \mathbb{N}$$

Furthermore, let

$$\sigma^{2}(s) = \operatorname{Var}(\xi_{1}(s)) + 2\sum_{i=2}^{\infty} \operatorname{Cov}(\xi_{1}(s), \xi_{i}(s)).$$

For fixed s, the process $\xi_i(s)$ is α -mixing with coefficients α_{i-2s} . Moreover, we have $E(|\xi_i(s)|^{2+\delta}) < \infty$ and $E(|\eta_i(s)|^{2+\delta}) < \infty$. Finally, one can show that

$$|\operatorname{Cov}(\eta_0(s), \eta_j(s))| = O\left(\alpha_{[j/3]}^{\delta/(2+\delta)} + \psi_{[j/3]}^{(1+\delta)/(2+\delta)}\right),$$

see Ibragimov and Linnik (1971). Observe that

$$(6) \qquad \left| \hat{B}_{n} - \sigma \right| \leq \left| \frac{1}{k} \sqrt{\frac{\pi}{2}} \sum_{i=1}^{k} \frac{|S_{i}(l,\xi) - l\overline{\xi}_{n}|}{\sqrt{l}} - \sigma(s) \right| + |\sigma - \sigma(s)| \\ + \frac{1}{k} \sqrt{\frac{\pi}{2}} \sum_{i=1}^{k} \frac{|S_{i}(l,\eta) - l\overline{\eta}_{n}|}{\sqrt{l}} \\ \leq \left| \frac{1}{k} \sqrt{\frac{\pi}{2}} \sum_{i=1}^{k} \frac{|S_{i}(l,\xi) - l\overline{\xi}_{n}|}{\sqrt{l}} - \sigma(s) \right| + |\sigma - \sigma(s)| \\ + \frac{1}{k} \sqrt{\frac{\pi}{2}} \sum_{i=1}^{k} \frac{|S_{i}(l,\eta) - lE(\eta_{1}(s))|}{\sqrt{l}} + \sqrt{l}|E(\eta_{1}(s)) - \overline{\eta}_{n}|.$$

We will now bound each of the terms on the right hand side separately. To the third term, we apply the inequality

$$E\left(\frac{S_{i}(l,\eta) - lE\eta_{1}(s)}{\sqrt{l}}\right)^{2} \leq \operatorname{Var}(\eta_{1}(s)) + 2\sum_{j=2}^{l} \left(1 - \frac{j}{l}\right) \operatorname{Cov}(\eta_{1}(s), \eta_{j}(s))$$
$$\leq (2N+1)\operatorname{Var}(\eta_{1}(s)) + 2\sum_{j=N}^{l} \left((\alpha_{j/3}^{\delta/(2+\delta)} + \psi_{j/3}^{(1+\delta)/(2+\delta)}\right),$$

valid for any $2 \le N \le l$. We fix N and choose s_0 sufficiently large such that for all $s \ge s_0$

$$E\left(\frac{S_i(l,\eta) - lE\eta_1(s)}{\sqrt{l}}\right)^2 \le \epsilon^2$$

and hence by Minkowski's inequality

$$\left\|\frac{1}{k}\sum_{i=1}^{k}\frac{|S_i(l,\eta) - lE(\eta_1(s))|}{\sqrt{l}}\right\|_2 \le \epsilon.$$

Since $\sigma(s) \to \sigma$, we also have $|\sigma(s) - \sigma| \leq \epsilon$ for all $s \geq s_0$ with s_0 sufficiently large. Proposition 3.1 implies that, for any fixed s,

$$\frac{1}{k}\sqrt{\frac{\pi}{2}}\sum_{i=1}^{k}\frac{|S_i(l,\xi)-l\,\overline{\xi}_n|}{\sqrt{l}}\to\sigma(s).$$

in L_2 as $n \to \infty$. Hence the first term on the right hand side of (6) converges to 0 in L_2 . Finally, stationarity and Lemma 4.2 imply $\sqrt{l} |\overline{\eta}_n - E(\eta_1(s))| \to 0$ in L_2 as $n \to \infty$. This finishes the proof of Theorem 1.1.

Proof of Theorem 1.2. As F is Lipschitz continuous, the process $(F(X_k))_{k\geq 1}$ satisfies the conditions of Theorem 1.1, hence $D_n \to \sigma_F$ in L_2 by Theorem 1.1. Thus it suffices to show

that $\hat{D}_n - D_n \to 0$ almost surely. We get

$$\begin{aligned} |D_n - \hat{D}_n| &\leq \frac{1}{[n/l_n]\sqrt{l_n}} \sqrt{\frac{\pi}{2}} \sum_{i=1}^{[n/l_n]} \left| T_i(l_n) - \hat{T}_i(l_n) - l_n(\bar{U}_n - \tilde{U}_n) \right| \\ &\leq \frac{\sqrt{\pi/2}}{[n/l_n]\sqrt{l_n}} \sum_{i=1}^{[n/l_n]} \left(\sum_{j=(i-1)l+1}^{il} |\hat{F}_n(X_j) - F(X_j)| + \frac{l_n}{n} \sum_{i=1}^n |\hat{F}_n(X_i) - F(X_i)| \right) \\ &\leq 2\sqrt{l_n} \sup_{t \in \mathbb{R}} |\hat{F}_n(t) - F(t)|. \end{aligned}$$

Lemma 4.4 implies $|D_n - \hat{D}_n| \to 0$ almost surely, provided $l_n = o(\frac{n}{\log \log n})$. This proves that \hat{D}_n is an L_2 consistent estimator of the limit variance σ_F .

4. AUXILIARY RESULTS

For ease of reference we state some results from the literature on weakly dependent processes that we need in the course of the proofs.

Lemma 4.1. (Yokoyama, 1980) Let $(X_i)_{i\geq 1}$ be a stationary sequence of random variables with $EX_1 = \mu$,

$$E|X_1|^{2+\delta} < \infty \quad and \quad \sum_{k=1}^{\infty} n^{\frac{t}{2}-1} \left(\alpha_k\right)^{\frac{2+\delta-t}{2+\delta}} < \infty,$$

for some $0 < \delta \leq \infty$ and $2 \leq t < 2 + \delta$. Then

$$E |\sum_{k=1}^{n} (X_i - \mu)|^t \le C n^{\frac{t}{2}} \left(E |X_1|^{2+\delta} \right)^{\frac{t}{2+\delta}}.$$

Lemma 4.2. (Shao and Yu, 1993) Let $(\xi_i)_{i\geq 1}$ be a sequence of random variables with $E\xi_n = 0$ and $\sup E\xi_n^2 < \infty$. Assume that there is a constant C > 0 such that $\sup E\left(\sum_{i=k+1}^{k+n} \xi_i\right)^2 \leq Cn$ for any $n \geq 1$. Then

$$\limsup \frac{\left|\sum_{i=1}^{n} \xi_{i}\right|}{\sqrt{n} \log^{2} n} = 0 \ a.s.$$

Lemma 4.3. (Ibragimov and Linnik, 1971) Let $(\xi_i)_{i\geq 1}$ be a stationary sequence of random variables with $E\xi_1 = 0$, $E|\xi_1|^{2+\delta} < \infty$ and $\sum_{k=1}^{\infty} (\alpha_k)^{\frac{\delta}{2+\delta}} < \infty$ for some $\delta > 0$. Then $\sigma^2 = E\xi_1^2 + 2\sum_{i=2}^{\infty} E(\xi_1\xi_i) < \infty$ and, in the case $\sigma^2 > 0$,

$$\frac{1}{\sigma\sqrt{n}}\left(\xi_1 + \dots + \xi_n\right) \xrightarrow{\mathcal{D}} N(0,1) \quad as \ n \to \infty.$$

Lemma 4.4. (Philipp, 1977) Let $(\xi_n)_{n\geq 1}$ be a stationary sequence of strongly mixing random variables with $\alpha_n = O(n^{-8})$, and let $\eta_n = f(\xi_n, \xi_{n+1}, \ldots)$, $n \geq 1$, be a sequence of functionals with common distribution function F(t), satisfying

$$\psi_m = E\left|\eta_n - E(\eta_n | \mathcal{F}_n^{n+m})\right| = O(m^{-12}),$$

where $\mathcal{F}_n^{n+m} = \sigma(\xi_n, \dots, \xi_{n+m})$. Then

$$\limsup_{n \to \infty} \sup_{t \in \mathbb{R}} \frac{\sqrt{n}(\hat{F}_n(t) - F(t))}{\sqrt{2 \log \log n}} \le c$$

almost surely, where $\hat{F}_n(t) = \frac{1}{n} \sum_{i=1}^n \mathbb{1}_{\{\eta_i \leq t\}}$.

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