

There Are No Nice Interfaces in (2 + 1)-Dimensional SOS Models in Random Media

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Received May 31, 1995

We prove that in dimension $d \leq 2$ translation-covariant Gibbs states describing rigid interfaces in a disordered solid-on-solid (SOS) cannot exist for any value of the temperature, in contrast to the situation in $d \geq 3$. The proof relies on an adaptation of a theorem of Aizenman and Wehr.

KEY WORDS: Disordered systems; interfaces; SOS model.

1. INTRODUCTION

In this note we want to conclude our analysis of the properties of interfaces in random environments by complementing our proof⁽²⁾ of the existence of Gibbs measures describing rigid interfaces in the SOS model with random surface tension (at low temperatures and weak disorder) in dimension $d \geq 3$ by showing that, on the contrary, in dimension $d \leq 2$, such Gibbs states cannot exist at any temperature as soon as there is any disorder present. In contrast to the technically rather involved existence proof, the proof of the converse statement is simple; in fact, it is a fairly straightforward application of a beautiful theorem of Aizenman and Wehr⁽¹⁾ which they used to prove the uniqueness of the Gibbs state in the two-dimensional random-field Ising model. For an extensive discussion of the history of the problem we refer to the introduction of our previous paper.⁽²⁾

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The model we consider is defined as follows. A surface is described by \mathbb{Z} -valued variables $h_x \in \mathbb{Z}$, $x \in \mathbb{Z}^d$. The Hamiltonian is given (formally) by

$$\mathcal{H}(h) = \sum_{\langle x, y \rangle} |h_x - h_y| + \varepsilon \sum_{x, k} \eta_x(k) \mathbb{1}_{h_x = k} \tag{1.1}$$

where $\{\eta_x(k)\}_{x \in \mathbb{Z}^d, k \in \mathbb{Z}}$ is a family of independent identically distributed random variables on some abstract probability space $(\Omega, \mathcal{F}, \mathbb{P})$, with non-degenerate distribution \mathbb{P} . We assume that $\mathbb{E}[\eta_x(k)] = 0$, $\mathbb{E}[\eta_x(k)^2] = 1$, where \mathbb{E} denotes the expectation w.r.t. the distribution \mathbb{P} . As a matter of fact, our result will apply to a far more general class of Hamiltonians, but we stick to the specific example for clarity. In ref. 2 we proved that under suitable conditions on the temperature and on the distribution \mathbb{P} , for $d \geq 3$, infinite-volume Gibbs states μ_H for this model can be constructed as weak limits of finite-volume Gibbs measures, where the heights on the boundary were set to a fixed and constant value H . This reflected the fact that ground states of the Hamiltonian with such boundary conditions tend to be mostly flat interfaces with only rare and localized fluctuations provoked by some large deviations of the random fields. In lower dimensions this is not expected to be the case; rather, on the basis of the Imry–Ma argument,⁽⁴⁾ fluctuations are expected to grow without bounds as the volumes increase, resulting in the fact that in the limit as the volume tends to infinity, the probability to observe the interface near the center of the volume at any given height should tend to zero, meaning that an infinite-volume Gibbs state does not exist. We want to prove a result that reflects this expectation.

To this end we define, following Aizenman and Wehr,⁽¹⁾ the random equivalent of translation-invariant Gibbs states, namely *translation-covariant* Gibbs states. Let us first note that in the context of random systems, the corresponding random Gibbs measures are most naturally viewed as Gibbs-measure-valued random variables on the space $(\Omega, \mathcal{F}, \mathbb{P})$, i.e., a measurable map from (Ω, \mathcal{F}) into the space of Gibbs measures on the measure space of the dynamical variables, in our case $(\mathbb{Z}^d, \mathcal{B})$, where \mathbb{Z}^d is equipped with the product topology of the discrete topology on \mathbb{Z} and \mathcal{B} is the corresponding finitely generated sigma-algebra (a recent exposition on some formal aspects of random Gibbs measures is given in ref. 6).

Definition 1.⁽¹⁾ A random Gibbs state $\mu(\eta)$ is called *translation covariant* iff it satisfies, almost surely, (i)

$$\begin{aligned} & \mu((\eta_A(h) + \Delta\eta_A(h), \eta_{A^c}(h))_{h \in \mathbb{Z}}(\cdot)) \\ &= \frac{\mu((\eta_A(h), \eta_{A^c}(h))_{h \in \mathbb{Z}}(\cdot \exp(-\beta\varepsilon \sum_{x \in A} \Delta\eta_x(h_x)))}{\mu((\eta_A(h), \eta_{A^c}(h))_{h \in \mathbb{Z}}(\exp(-\beta\varepsilon \sum_{x \in A} \Delta\eta_x(h_x)))} \end{aligned} \tag{1.2}$$

for any finite-volume perturbation $\Delta\eta_A(h)$ of the random fields; and (ii)

$$\begin{aligned} &\mu((\eta_{x+y}(h))_{x \in \mathbb{Z}^d, h \in \mathbb{Z}})(f(h_x)_{x \in \mathbb{Z}^d}) \\ &= \mu((\eta_x(h))_{x \in \mathbb{Z}^d, h \in \mathbb{Z}})(f(h_{x-y})_{x \in \mathbb{Z}^d}) \end{aligned} \tag{1.3}$$

for all $y \in \mathbb{Z}^d$.

Let us note that if one translation-covariant Gibbs state, say μ_0 , exists, than there exists an infinite family of them, μ_H , for all $H \in \mathbb{Z}$, where

$$\begin{aligned} &\mu_H((\eta_x(h))_{x \in \mathbb{Z}^d, h \in \mathbb{Z}})(f(h_x)_{x \in \mathbb{Z}^d}) \\ &= \mu_0((\eta_x(h+H))_{x \in \mathbb{Z}^d, h \in \mathbb{Z}})(f(h_x+H)_{x \in \mathbb{Z}^d}) \end{aligned} \tag{1.4}$$

We will prove the following theorem:

Theorem 1. Suppose that the distribution \mathbb{P} of $\eta_x(h)$ either (i) has no isolated atoms or (ii) has compact support; then, if $d \leq 2$, $\varepsilon \neq 0$, for all $\beta < \infty$, the SOS model defined through (1.1) does not permit translation-covariant random Gibbs states.

Remark. Translation-covariant Gibbs states are the nice things one expects to get as weak limits with simple boundary conditions, which in particular should not be too knowledgeable of the disorder. In particular, property (1.2) can only be violated if μ_H was constructed as a weak limit with boundary conditions that depended on the random fields in the finite set A . It is quite conceivable that rather artificial Gibbs states violating the conditions (1.2) and (1.3) can be constructed in this model. For example, it might be possible to choose a sequence of volumes $A_n \uparrow \mathbb{Z}^d$ and a sequence of random boundary conditions carefully in such a way as to ensure that the corresponding ground states have height $h_0 = 0$ at the origin. It is conceivable that such a sequence of measures could converge, but clearly they are “physically” irrelevant.

Remark. To prove Theorem 1 we will show that the assumption of translation-covariant Gibbs states leads to a contradiction. One might hope that a more direct approach based, e.g., on the renormalization group method could also work and give more precise information on finite-volume quantities. Such an approach, however, appears to be exceedingly difficult. In ref. 5 a result on the absence of stable interfaces based on that idea was proven, but only in a specific mean-field-type limit of a hierarchical model. The reader may find it instructive to study that paper, since it hints at the complexities occurring in the problem.

2. PROOF OF THE THEOREM

We will show that the assumption that there exist translation-covariant states in $d \leq 2$ leads to a contradiction. Having realized what it is that we want to prove, the adaptation of the arguments of Aizenman and Wehr to our situation is almost trivial. To do so, we define the “order parameters”

$$M(h, h') \equiv \mathbb{E}[\mu_0(h_x = h)] - \mathbb{E}[\mu_0(h_x = h')] \tag{2.1}$$

The point here is that if these quantities vanish, then then we have the following contradiction:

$$1 = \mathbb{E} \sum_{h \in \mathbb{Z}} \mu_0(h_x = h) = \sum_{h \in \mathbb{Z}} \mathbb{E} \mu_0(h_x = h) = \sum_{h \in \mathbb{Z}} \mathbb{E} \mu_0(h_x = h') \tag{2.2}$$

for any h' . In fact, if h^* denotes any value for which $\mathbb{E} \mu_0(h_x = h^*) > 0$, to arrive at the same contradiction it is enough to show that there exists an infinite number of values h such that $M(h^*, h) = 0$.

Thus to prove the theorem, we only have to show that this is the case. Let us define, for fixed h, H, β , and finite volume Λ , the generating functions

$$\begin{aligned} \Gamma_\Lambda(h, H) \equiv & \frac{1}{\beta} \mathbb{E} \left[\ln \mu_0 \left(\exp \left(\beta \varepsilon \sum_{x \in \Lambda} \eta_x(h_x) \right) \right) \right. \\ & \left. - \ln \mu_H \left(\exp \left(\beta \varepsilon \sum_{x \in \Lambda} \eta_x(h_x) \right) \right) \middle| \mathcal{F}_{\Lambda, h} \right] \end{aligned} \tag{2.3}$$

where $\mathcal{F}_{\Lambda, h}$ denotes the sigma-algebra that is generated by the random variables $\{\eta_x(h)\}_{x \in \Lambda}$. Define further the random variable

$$\tau_x(h, H) = \mathbb{E}[\mu_0(h_x = h) - \mu_H(h_x = h) | \mathcal{F}_{\mathbb{Z}^d, h}] \tag{2.4}$$

Then we have the following result.

Lemma 1. The functions $\Gamma_\Lambda(h, H)$ and $\tau_x(h, H)$ have the following properties:

(0) We have

$$\tau_z(h, H)((\eta_{x+y}(h))_{x \in \mathbb{Z}^d}) = \tau_{z-y}(h, H)((\eta_x(h))_{x \in \mathbb{Z}^d}) \tag{2.5}$$

(i) For all $x \in \Lambda$

$$\frac{\partial}{\partial \eta_x(h)} \Gamma_\Lambda(h, H) = \varepsilon \mathbb{E}[\tau_x(h, H) | \mathcal{F}_{\Lambda, h}] \tag{2.6}$$

(ii) We have

$$\mathbb{E}[\tau_x(h, H)] = M(h, h - H) \tag{2.7}$$

(iii) For all positive β and ε

$$|\tau_x(h, H)| \leq 1 \tag{2.8}$$

and

$$\left| \frac{\partial}{\partial \eta_x(h)} \tau_x(h, H) \right| \leq \frac{\varepsilon \beta}{4} \tag{2.9}$$

(iv) We have

$$\mathbb{E}[\Gamma_A(h, H)] = 0 \tag{2.10}$$

Proof. (2.5) follows from (1.3). Equation (2.6) follows from (1.2). Equation (2.7) is a consequence of the “covariance w.r.t. height shift” expressed by (1.4). The bound (2.8) is obvious. To prove (2.9), just note that

$$\begin{aligned} & \frac{\partial}{\partial \eta_x(h)} \tau_x(h, H) \\ &= \varepsilon \beta \mathbb{E}[\mu_0(h_x = h) - \mu_0(h_x = h)^2 - \mu_H(h_x = h) + \mu_H(h_x = h)^2 | \mathcal{F}_{\mathbb{Z}^d, h}] \end{aligned} \tag{2.11}$$

(2.10) follows again from (1.4). ■

Lemma 1 ensures that we are in the situation of ref. 1, Proposition 6.1, which allows us to bound the fluctuations of $\Gamma_A(h, H)$ from below. In particular we have from Proposition 6.1

$$\liminf_{A = [-L, L]^d, L \uparrow \infty} \mathbb{E}[\exp(t\Gamma_A(h, H)/\sqrt{|A|})] \geq \exp\left(\frac{t^2 b^2}{2}\right) \tag{2.12}$$

where [see ref. 1, Eq. (6.24)]

$$b^2 \geq \mathbb{E}[\mathbb{E}[\Gamma_A(h, H) | \mathcal{F}_{0, h}]^2] \tag{2.13}$$

We distinguish the cases (i) and (ii) in the hypothesis of our theorem. In case (i), Eq. (A.3.2) and Proposition A.3.2, case (ii), of ref. 1 immediately give that

$$b \geq \varepsilon \theta_p(M(h, H), 1/(\varepsilon \beta)) > 0 \tag{2.14}$$

if $M(h, H) \neq 0$.

Under the assumption of case (ii), we show the following.

Lemma 2. Let h^* be such that $\mathbb{E}\mu_0(h_x = h^*) > 0$. Then there exists $H_0 < \infty$ such that for all $H \geq H_0$

$$b \geq \varepsilon \gamma_{\mathbb{P}}(M(h^*, H), 1/(\varepsilon\beta)) > 0 \tag{2.15}$$

if $M(h^*, H) \neq 0$.

Proof. From Proposition A.3.2, case (iii), of ref. 1, condition (2.15) follows if the function

$$\eta_0(h^*) \mapsto g(\eta_0(h^*)) \equiv \mathbb{E}[\Gamma(h, H) | \mathcal{F}_{0,h^*}](\eta_0(h^*))$$

is monotone for all $\eta_0(h^*) \in [A, B]$, where $[A, B]$ is the convex hull of the support of the one-field distribution \mathbb{P} .

To prove the monotonicity, we proceed as follows. From (2.6) we get

$$\begin{aligned} \frac{\partial g}{\partial \eta_0(h^*)} &= \varepsilon \mathbb{E}[\tau_x(h^*, H) | \mathcal{F}_{0,h^*}] \\ &= \varepsilon \mathbb{E}[\mu_0(h_x = h^*) | \mathcal{F}_{0,h^*}] - \varepsilon \mathbb{E}[\mu_H(h_x = h^*) | \mathcal{F}_{0,h^*}] \end{aligned} \tag{2.16}$$

It is easy to see that (1.3) implies the deterministic bounds

$$\begin{aligned} &\delta_H \exp(-2\beta\varepsilon(B - A)) \\ &\leq \mathbb{E}[\mu_H(h_x = h^*) | \mathcal{F}_{0,h^*}](\eta_0(h^*)) \leq \delta_H \exp(2\beta\varepsilon(B - A)) \end{aligned} \tag{2.17}$$

for all $\eta_0(h^*) \in [A, B]$, where $\delta_H \equiv \mathbb{E}[\mu_H(h_x = h^*)]$. Since

$$\sum_{H \in \mathbb{Z}} \delta_H = \sum_{H \in \mathbb{Z}} \mathbb{E}[\mu_0(h_x = h^* - H)] = 1 \tag{2.18}$$

there exists H_0 such that $\delta_H \leq \delta_0 \exp(-4\beta\varepsilon(B - A))$ for all $H \geq H_0$. This implies by (2.16) the desired monotonicity for all $H \geq H_0$. ■

To conclude the proof of the theorem, we thus only have to show that (2.9) with $b^2 > 0$ leads to a contradiction. This relies on the following lemma:

Lemma 3. We have

$$|\Gamma_A(h, H)| \leq |H| \cdot |\partial A| \tag{2.19}$$

where $|\partial A| = |\{(x, y) | x \in A, y \in A^c, \|x - y\|_2 = 1\}|$.

In fact, (2.19) implies

$$\mathbb{E}[\exp(t\Gamma_A(h, H)/\sqrt{|A|})] \leq \exp\left(|t| \cdot |H| \frac{|\partial A|}{\sqrt{|A|}}\right) \tag{2.20}$$

which contradicts (2.12) if A is chosen as, e.g., a d -dimensional cube and $d \leq 2$. This concludes the proof of the theorem, if we assume Lemma 3. ■

To conclude, we prove Lemma 3.

Proof of Lemma 3. We focus on one summand in (2.2) and write

$$\begin{aligned}
 & \mathbb{E} \left[\ln \mu_H((\eta_A(h), \eta_{A^c}(h))_{h \in \mathbb{Z}}) \left(\exp \left(\beta \varepsilon \sum_{x \in A} \eta_x(h_x) \right) \right) \middle| \mathcal{F}_{A,h} \right] \\
 &= -\mathbb{E} \left[\ln \mu_H((0_A, \eta_{A^c}(h))_{h \in \mathbb{Z}}) \left(\exp \left(-\beta \varepsilon \sum_{x \in A} \eta_x(h_x) \right) \right) \middle| \mathcal{F}_{A,h} \right] \\
 &= -\mathbb{E} \left[\ln \mu_H((0_A, \eta_{A^c}(h-H))_{h \in \mathbb{Z}}) \left(\exp \left(-\beta \varepsilon \sum_{x \in A} \eta_x(h_x) \right) \right) \middle| \mathcal{F}_{A,h} \right] \\
 &= -\mathbb{E} \left[\ln \mu_0((0_A, \eta_{A^c}(h))_{h \in \mathbb{Z}}) \left(\exp \left(-\beta \varepsilon \sum_{x \in A} \eta_x(h_x + H) \right) \right) \middle| \mathcal{F}_{A,h} \right]
 \end{aligned} \tag{2.21}$$

where the first equality is due to the transformation law (1.2) w.r.t. local perturbations, the second to the stationarity of the distribution of the random fields under the shift $h_x \mapsto h_x + H$ for $x \in A^c$, and the third to (1.4).

Let us now employ the DLR equations⁽³⁾ to write

$$\begin{aligned}
 & \mu_0((0_A, \eta_{A^c}(h))_{h \in \mathbb{Z}}) \left(\exp \left(-\beta \varepsilon \sum_{x \in A} \eta_x(h_x + H) \right) \right) \\
 &= \int \mu_0((0_A, \eta_{A^c}(h))_{h \in \mathbb{Z}}) (d\bar{h}_{A^c}) \left[\sum_{h_A \in \mathbb{Z}^A} \exp \left(-\beta \sum_{\substack{\langle x,y \rangle \\ x,y \in A}} |h_x - h_y| \right. \right. \\
 & \quad \left. \left. - \beta \sum_{\substack{\langle x,y \rangle \\ x \in A, y \in A^c}} |h_x - \bar{h}_y| - \beta \varepsilon \sum_{x \in A} \eta_x(h_x + H) \right) \right] \\
 & \quad \times \left[\sum_{h_A \in \mathbb{Z}^A} \exp \left(-\beta \sum_{\substack{\langle x,y \rangle \\ x,y \in A}} |h_x - h_y| - \beta \sum_{\substack{\langle x,y \rangle \\ x \in A, y \in A^c}} |h_x - \bar{h}_y| \right) \right]^{-1} \tag{2.22}
 \end{aligned}$$

Note that only the numerator is H dependent. Therefore we introduce $h'_x = h_x + H$ for $x \in A$, and estimate the boundary term in the ‘surface energy’ in the exponential in the numerator uniformly by

$$\begin{aligned} \sum_{\substack{\langle x, y \rangle \\ x \in A, y \in A^c}} |h_x - \bar{h}_y| &= \sum_{\substack{\langle x, y \rangle \\ x \in A, y \in A^c}} |h'_x - \bar{h}_y - H| \\ &\leq \sum_{\substack{\langle x, y \rangle \\ x \in A, y \in A^c}} |h'_x - \bar{h}_y| + |H| \cdot |\partial A| \end{aligned} \tag{2.23}$$

and

$$\sum_{\substack{\langle x, y \rangle \\ x \in A, y \in A^c}} |h_x - \bar{h}_y| \geq \sum_{\substack{\langle x, y \rangle \\ x \in A, y \in A^c}} |h'_x - \bar{h}_y| - |H| \cdot |\partial A| \tag{2.24}$$

From this we have

$$\begin{aligned} \sum_{h_A \in \mathbb{Z}^A} \exp \left(-\beta \sum_{\substack{\langle x, y \rangle \\ x, y \in A}} |h_x - h_y| - \beta \sum_{\substack{\langle x, y \rangle \\ x \in A, y \in A^c}} |h_x - \bar{h}_y| - \beta \varepsilon \sum_{x \in A} \eta_x(h_x + H) \right) \\ \leq \exp(\beta |H| \cdot |\partial A|) \sum_{h'_A \in \mathbb{Z}^A} \exp \left(-\beta \sum_{\substack{\langle x, y \rangle \\ x, y \in A}} |h'_x - h'_y| \right. \\ \left. - \beta \sum_{\substack{\langle x, y \rangle \\ x \in A, y \in A^c}} |h'_x - \bar{h}_y| - \beta \varepsilon \sum_{x \in A} \eta_x(h'_x) \right) \end{aligned} \tag{2.25}$$

and a similar lower bound. Substituting these bounds in (2.12) and comparing the $H = 0$ term gives (2.10) directly. ■

To summarize the gist of the proof, Lemma 3 roughly states that when we deform an interface over a local region A by shifting it up by a distance H , then this ‘costs’ no more than to build a boundary wall, i.e., $H |\partial A|$. On the other hand, the Aizenman–Wehr theorem says that there are always regions where such a price is compensated by a corresponding gain in random energy. In that sense, the proof really builds along the Imry–Ma argument. On the other hand, we see that to make this argument rigorous, one has to proceed quite carefully in order to avoid possible pathologies that could be produced by very ‘exotic’ constructions of Gibbs states. This somewhat restricts the generality of our statement (namely that we only exclude translation-covariant Gibbs states rather than ‘any’ Gibbs states), but such a restriction does not appear physically unreasonable.

ACKNOWLEDGMENTS

This work was partially supported by the Commission of the European Communities under contracts CHRX-CT93-0411 and CHBGT-CT93-0244.

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Communicated by J. L. Lebowitz